

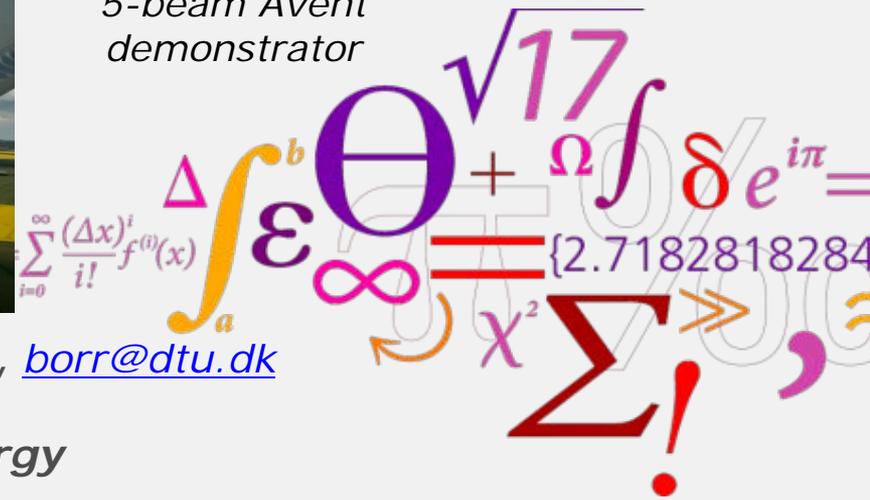
# Near flow measurement with nacelle lidars: the future of performance verification?

**v infinity is found!**



*ZephIR Dual-Mode*

*5-beam Avent  
demonstrator*



*A. Borraccino, R. Wagner, DTU Wind Energy, [borr@dtu.dk](mailto:borr@dtu.dk)*

*D. Schlipf, F. Haizmann, Stuttgart Wind Energy*



# Does this make it any easier?



Perdigão.  
credit: N. Vasiljevic

- In complex terrain:
  - any “free stream” wind speed idea?
  - site calibration? Maybe

# Does this make it any easier?

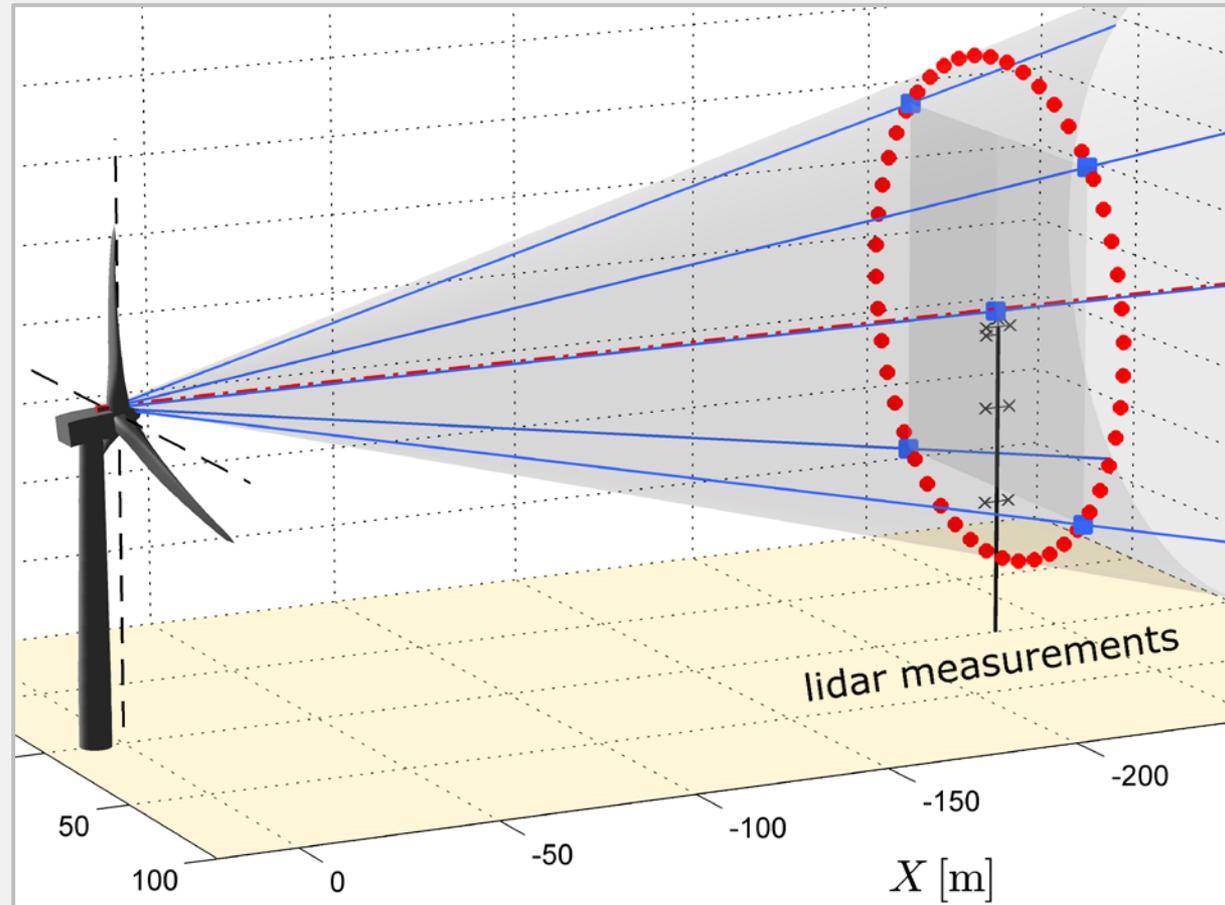


- Offshore:
  - most expensive
  - free wind may not be measurable due to wakes

# Power performance verification: nacelle-mounted lidars, the future?

- Several possibilities for lidar measurements:

1) 2.5D distance fitting wind speed + direction + shear to lidar-measured LOS velocities



# Power performance verification: nacelle-mounted lidars, the future?

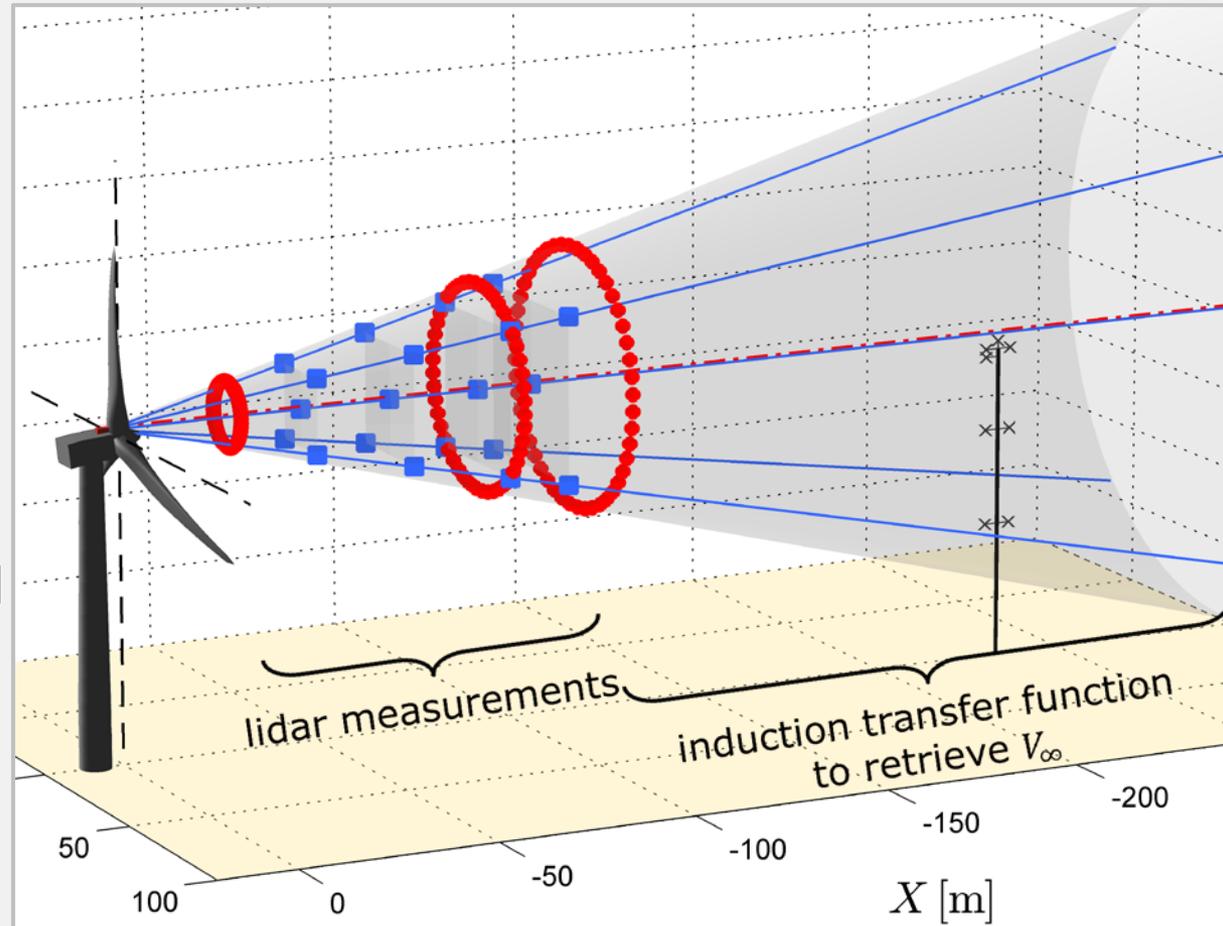
- Several possibilities for lidar measurements:

1) 2.5D distance fitting  
 fitting wind speed + direction + shear to lidar-measured LOS velocities

2) Multiple distances close to rotor  
 induction integrated in wind field reconstruction

$$\frac{U(x)}{U_\infty} = 1 - a \left( 1 + \frac{\xi}{\sqrt{1+\xi^2}} \right)$$

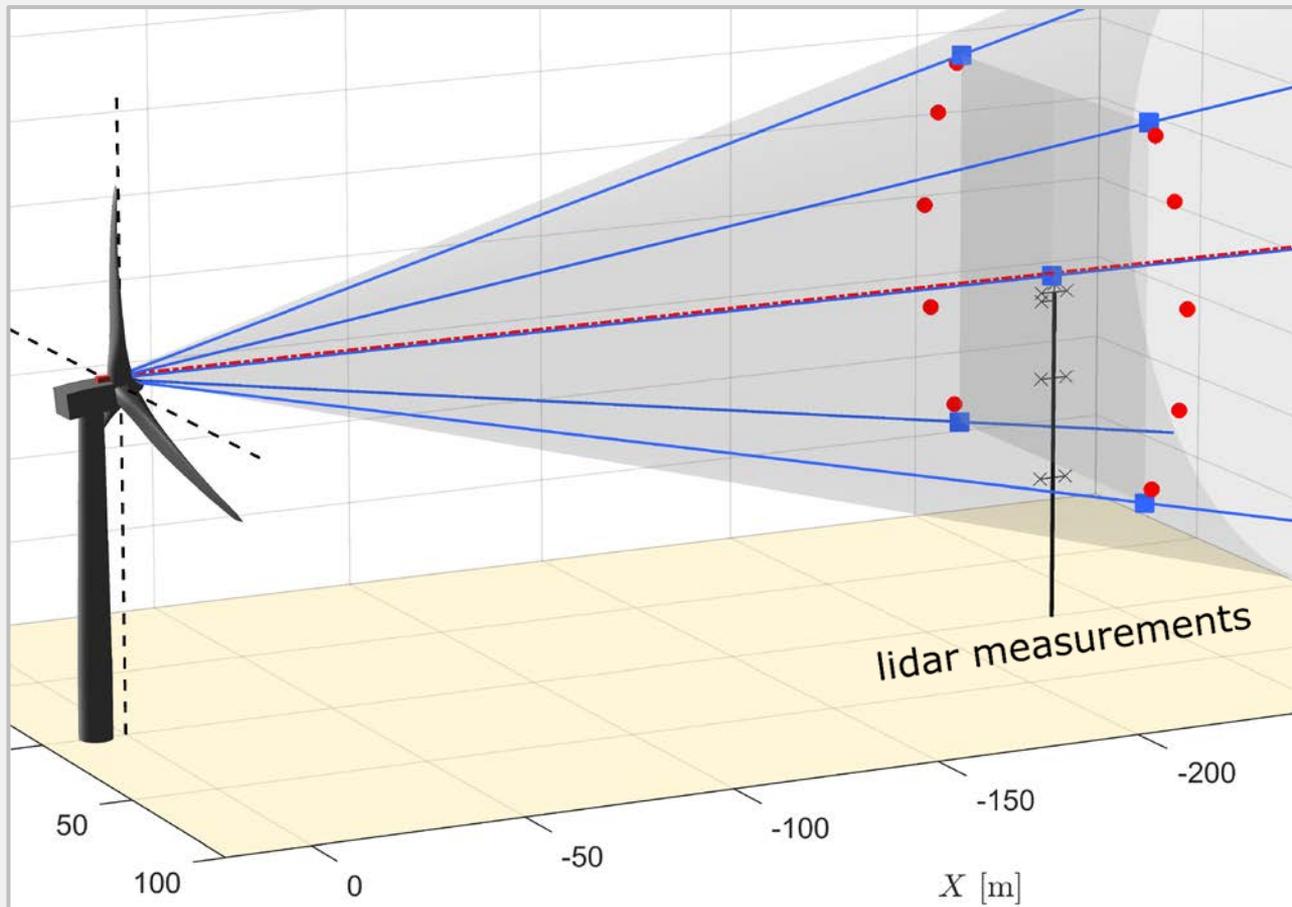
$$a = \frac{1}{2} \left( 1 - \sqrt{1 - C_t} \right)$$



# Case 1: lidar meas. @2.5D

**5B-Demo:** use the 5 pts

**ZDM:** use 10 pts



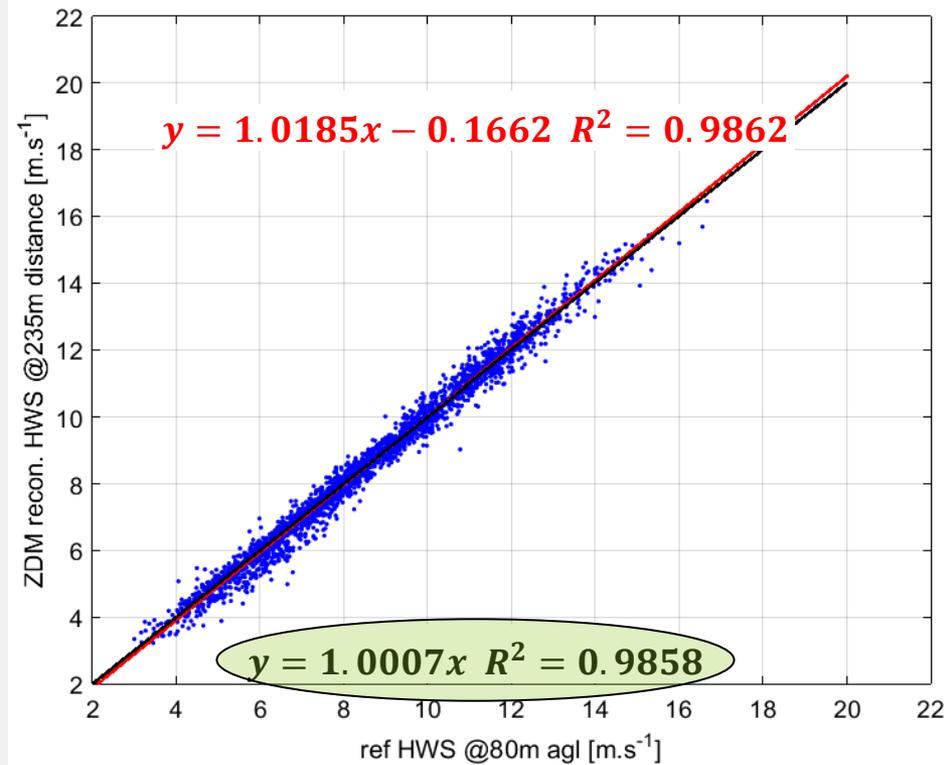
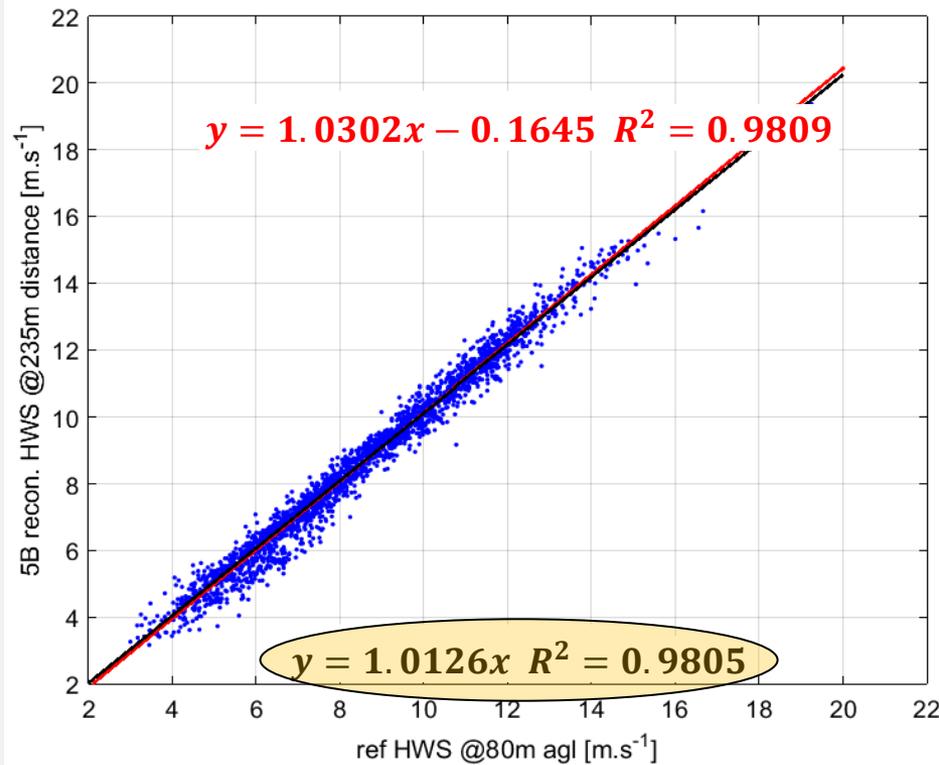
# Case 1: lidar meas. @2.5D

Mast comparison

**5B-Demo:** use the 5 pts

**ZDM:** use 10 pts

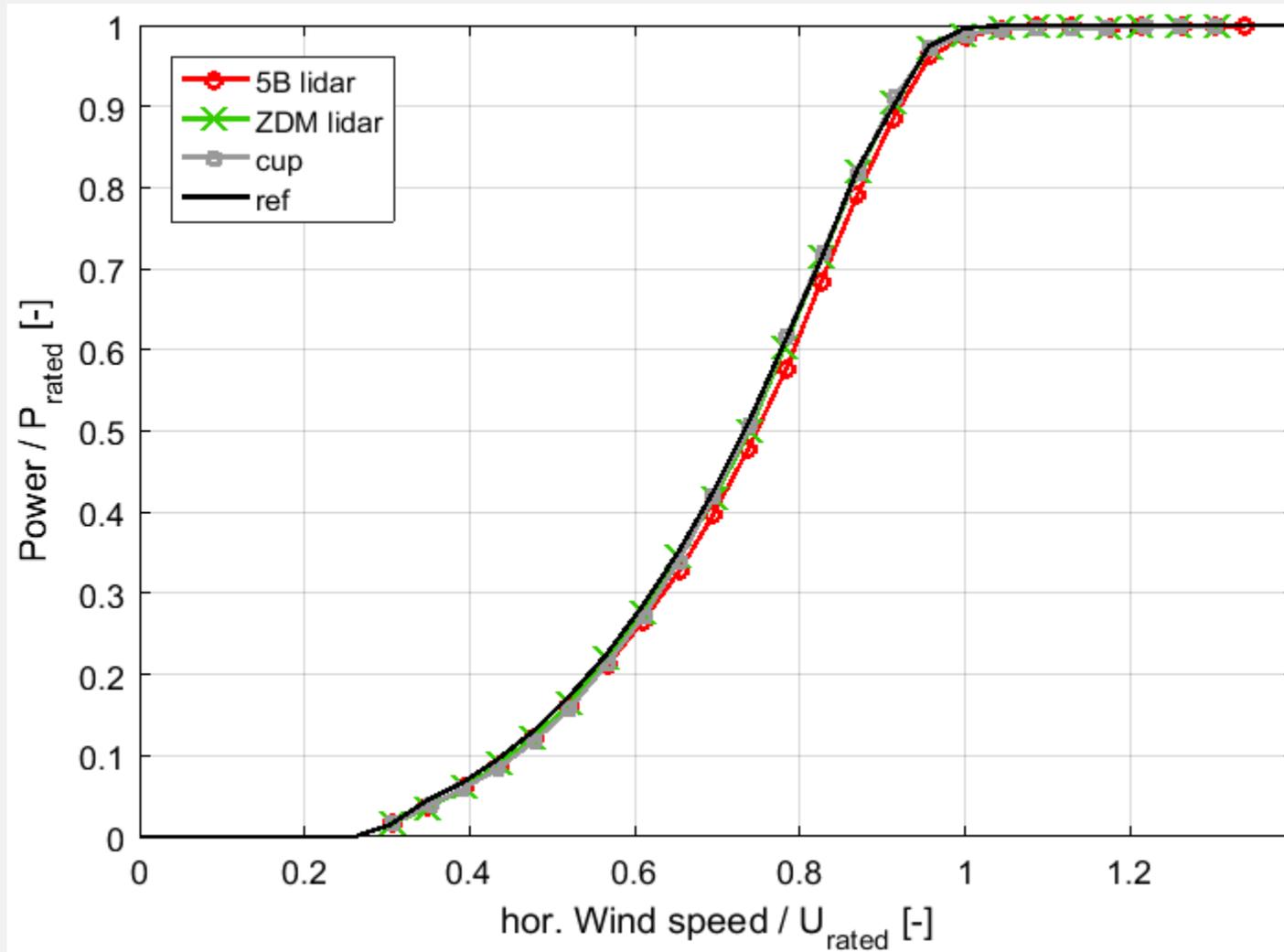
HWS estimated @hub height



$N_{points} = 2563$

# Case 1: lidar meas. @2.5D

## Power curves

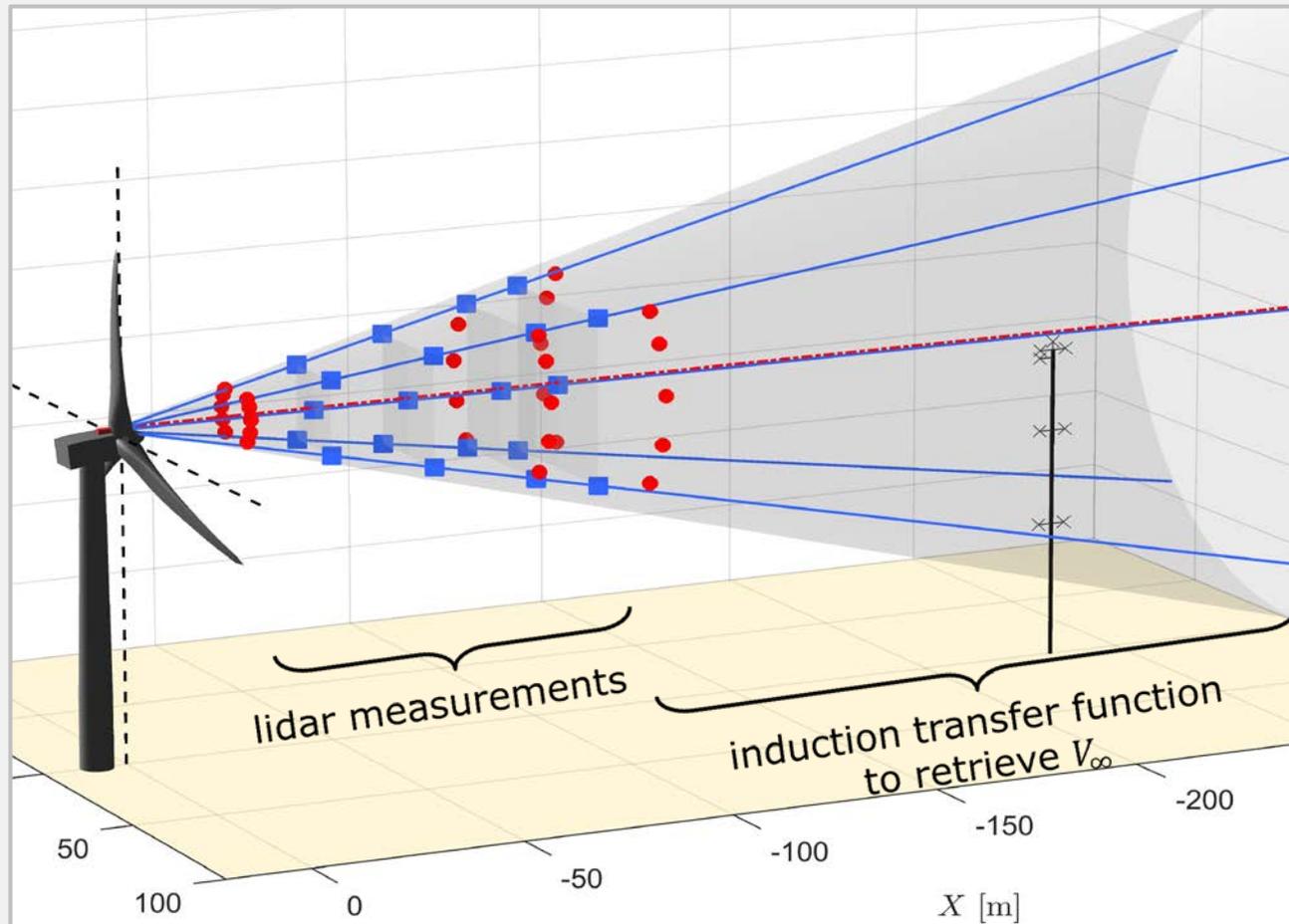


# Case 2: lidar meas.

@ multiple distances close to rotor

**5B-Demo** : use the 5 pts  
 @[0.5 0.75 1.0 1.15] D

**ZDM**: use 10 pts  
 @[0.3 1.0 1.25] D



# Case 2: lidar meas. @ multi-dist (near flow)

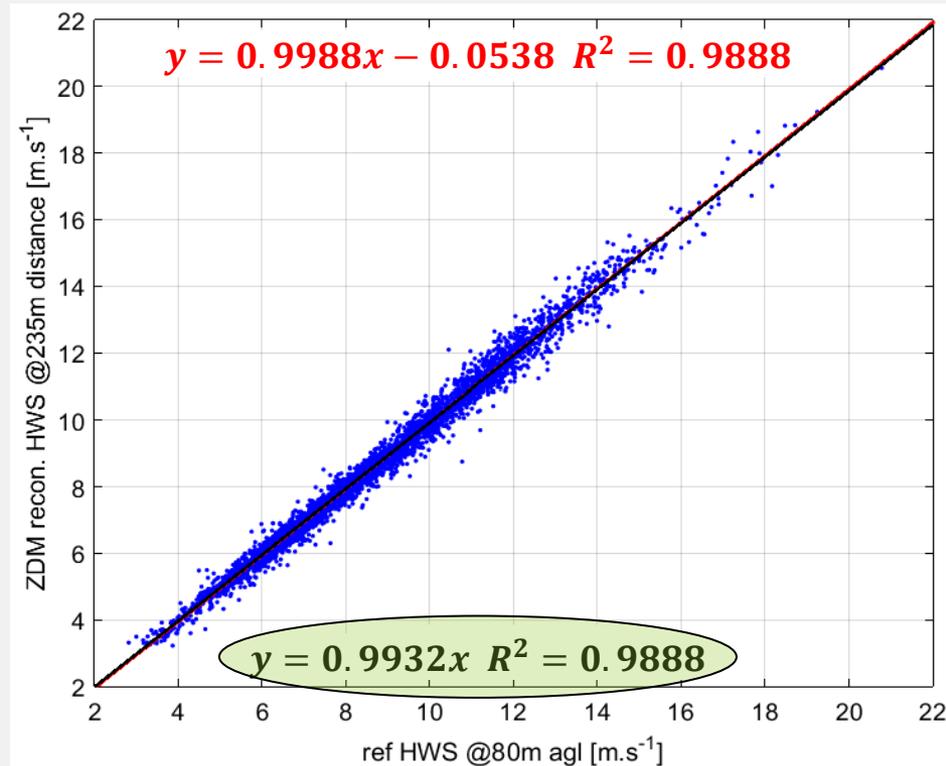
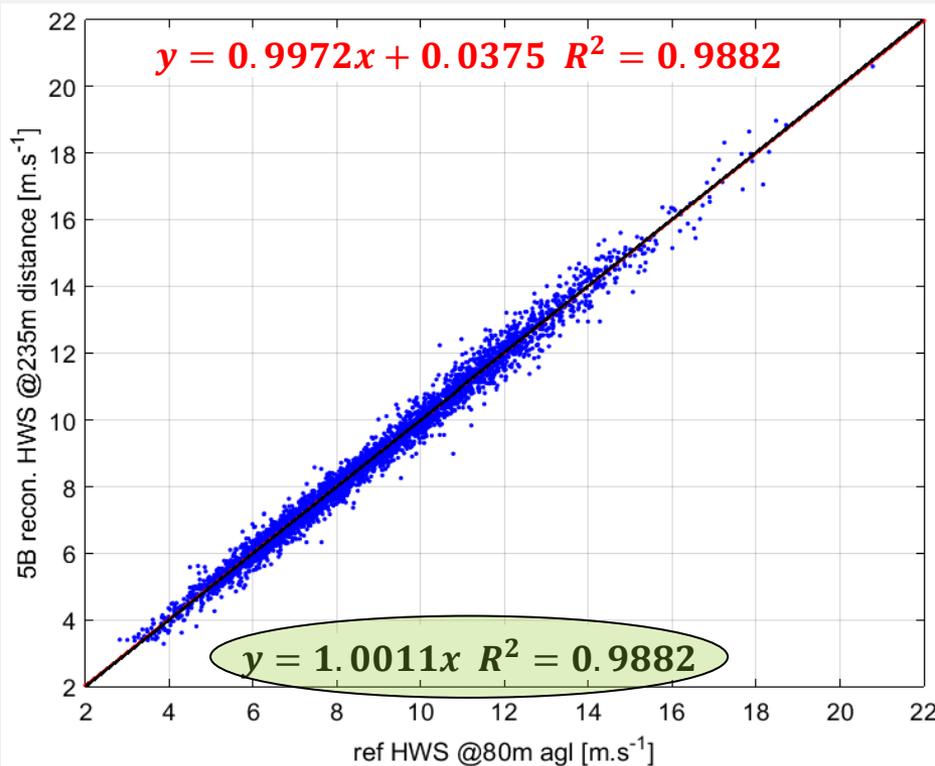
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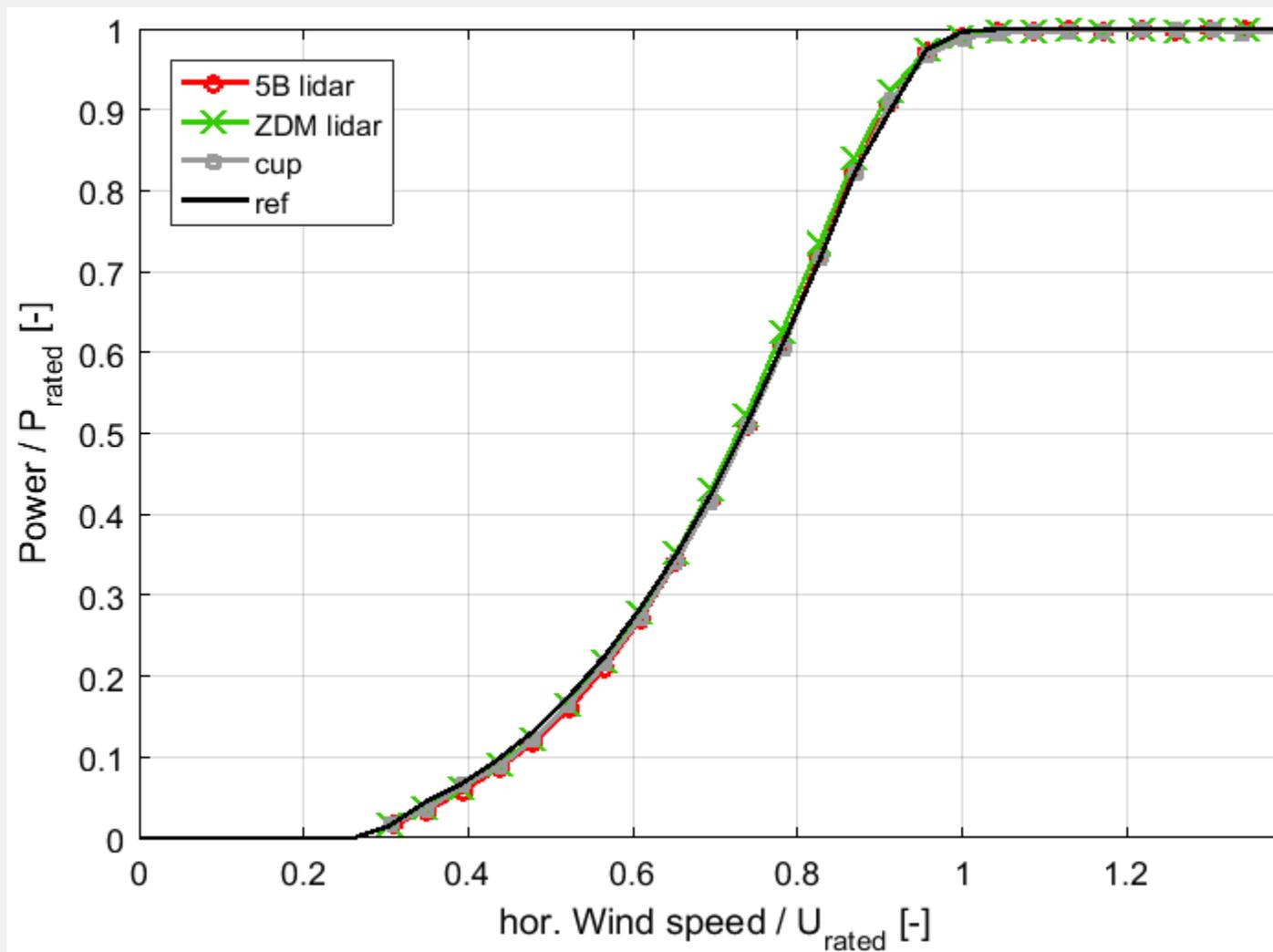
HWS estimated @hub height and @2.5D distance



$N_{points} = 4028$

# Case 2: lidar meas. @ multi-dist (near flow)

## Power curves



# AEP results

- IEC -12-1 methodology
- extrapolated AEPs
- 0.5 m/s bin width
- Relative difference in % of cup-based AEP

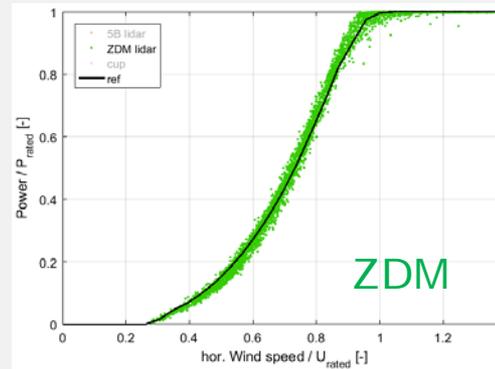
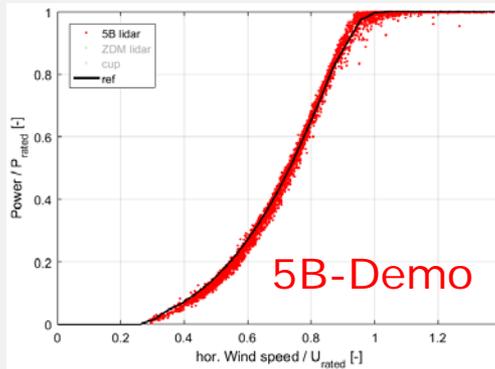
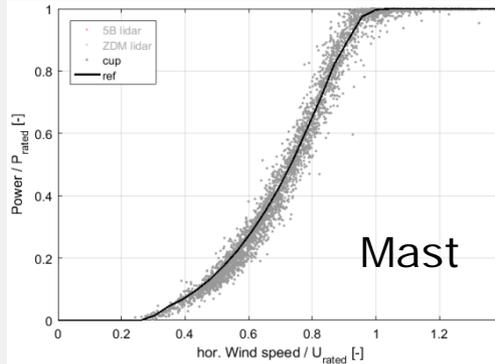
<b>Lidar measurements</b>	<b>@2.5 D</b> (case 1)			<b>@multiple distances</b> (case 2)		
<b>Rayleigh avg wind speed</b>	<b>6 m/s</b>	<b>8 m/s</b>	<b>10 m/s</b>	<b>6 m/s</b>	<b>8 m/s</b>	<b>10 m/s</b>
Avent 5-Beam demonstrator lidar	Wspeed difference: +1.2%			Wspeed difference: +0.1%		
	-2.0%	-1.6%	-1.2%	-0.4%	-0.1%	+0.0%
Zephir Dual Mode lidar	Wspeed difference: +0.1%			Wspeed difference: -0.7%		
	+0.4%	+0.2%	+0.1%	+2.0%	+1.3%	+0.9%

➔ AEP estimations as good with the “multi-distances” method as with the 2.5D (<1.5% difference)

# Take-aways

- **$V_\infty$  is found!** The solution: measurements close to rotor, within the induction zone, at multiple distances, e.g. with nacelle lidars
- Wind Field Reconstruction algo. provide estimates comparable classic mast instrumentation (< 1% difference)
- Power curves in flat terrain verified accurately, reduced scatter (as usual with nacelle lidars)
  - next generation of IEC61400-12-1 standards? (NWIP)
- **Further work** :
  - Two-dimensional induction? (ongoing)
  - Adaptation and testing of method in complex terrain (campaign in Hill of Towie, Zephir DM+4-beam Wind Iris)
  - Uncertainty assessment of Wind Field Characteristics: speed, direction, shear, induction factor /  $C_t$ , ...

# Thanks for your attention!



More info:

- website [www.unitte.dk](http://www.unitte.dk)
- contact [borr@dtu.dk](mailto:borr@dtu.dk)

# Acknowledgements



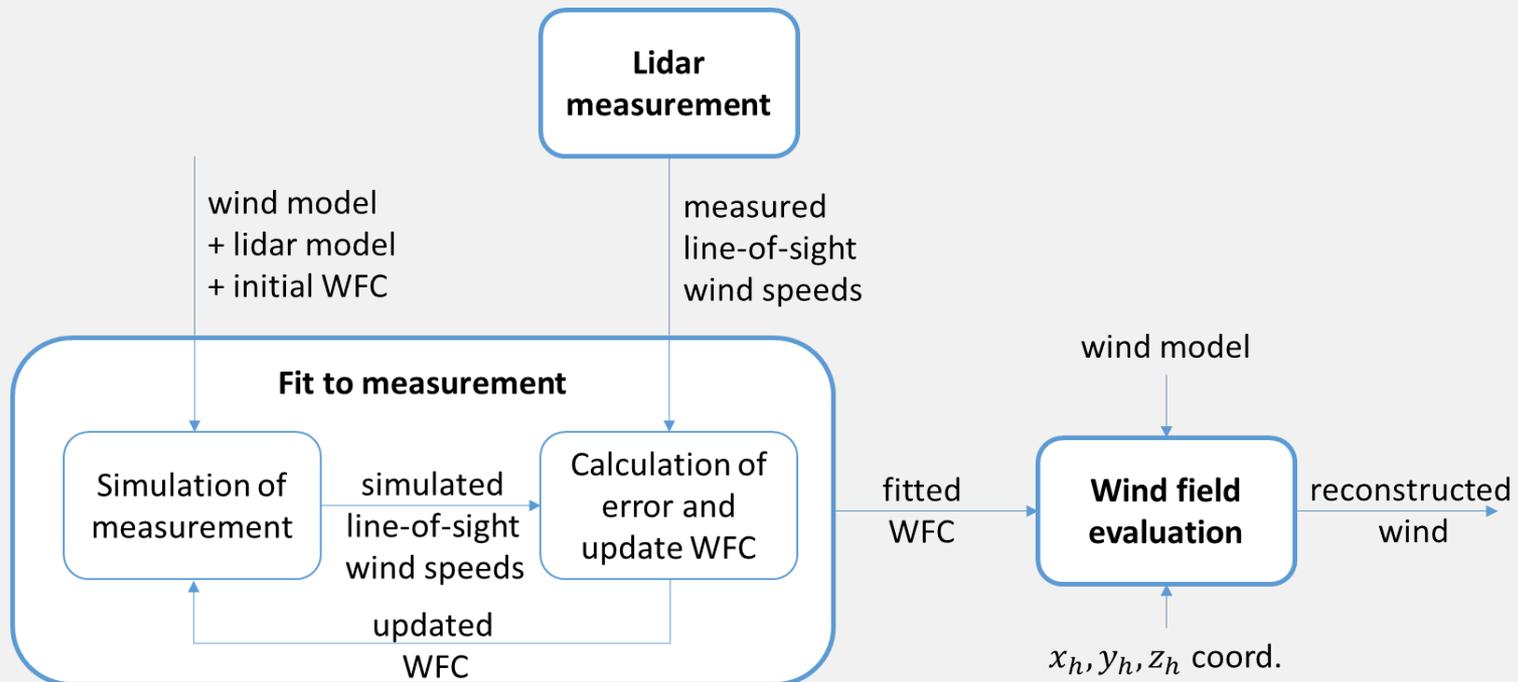
This work was performed within the UniTTe project ([www.unitte.dk](http://www.unitte.dk)) which is financed by Innovation Fund Denmark.

# Model-based wind field reconstruction

- **Doppler wind LiDaRs do not...**
  - ...measure wind speed, wind direction, shear, ...**
- see [Hardesty, 1987](#) (wonderful description of lidar principles)

- **They:**

- only measure LOS velocities
- estimate/reconstruct wind field characteristics (WFC)



# Model-based wind field reconstruction

- **Modelling the wind field**

- choose a wind model that fits the application & site characteristics
- the reconstruction should be performed either in the WIND coordinate systems or in the HUB

- **For power performance: static models**

- i.e. no time dependency
- use 10-min averages of:
  - LOS velocities
  - inclinometers readings
- use knowledge of the trajectory (opening angles, ranges config) and of lidar position

# Model-based wind field reconstruction

## • Wind models

Model	$U$	$V$	$W$	comment
Homogeneous 2D	$U_w = cst \leftrightarrow U_I = U$	$V_w = 0 \leftrightarrow V_I = V$	$W_w = 0 \leftrightarrow W_I = 0$	Does not depend on $X, Y, Z$
Homogeneous 3D	$U_w = cst \leftrightarrow U_I = U$	$V_w = 0 \leftrightarrow V_I = V$	$W_w = 0 \leftrightarrow W_I = W$	Does not depend on $X, Y, Z$
Inhomogeneous 2D + linear V shear	$U_w = v_0 + \delta_V \cdot (z_w - z_{hub})$ $\leftrightarrow U_I = f(z)$	$V_w = 0 \leftrightarrow V_I = V$	$W_w = 0 \leftrightarrow W_I = 0$	Yaw misalignment $\alpha_H = cst$
Inhomogeneous 2D + linear V shear + linear V veer	$U_w = v_0 + \delta_V \cdot (z_w - z_{hub})$ $\leftrightarrow U_I = f(z)$	$V_w = 0 \leftrightarrow V_I = f(z)$	$W_w = 0 \leftrightarrow W_I = 0$	Yaw misalignment $\alpha_H = f(z)$
<b>Inhomogeneous 2D + power law shear</b>	$U_w = v_0 (z_w / z_{hub})^{\alpha_{exp}}$ $\leftrightarrow U_I = f(z)$	$V_w = 0 \leftrightarrow V_I = V$	$W_w = 0 \leftrightarrow W_I = 0$	<b>Yaw misalignment</b> $\alpha_H = cst$

↳ fitted wind characteristics are:

- HWS  $v_0$
- yaw misalignment  $\alpha_H$  (relative wind dir)
- shear exponent  $\alpha_{exp}$

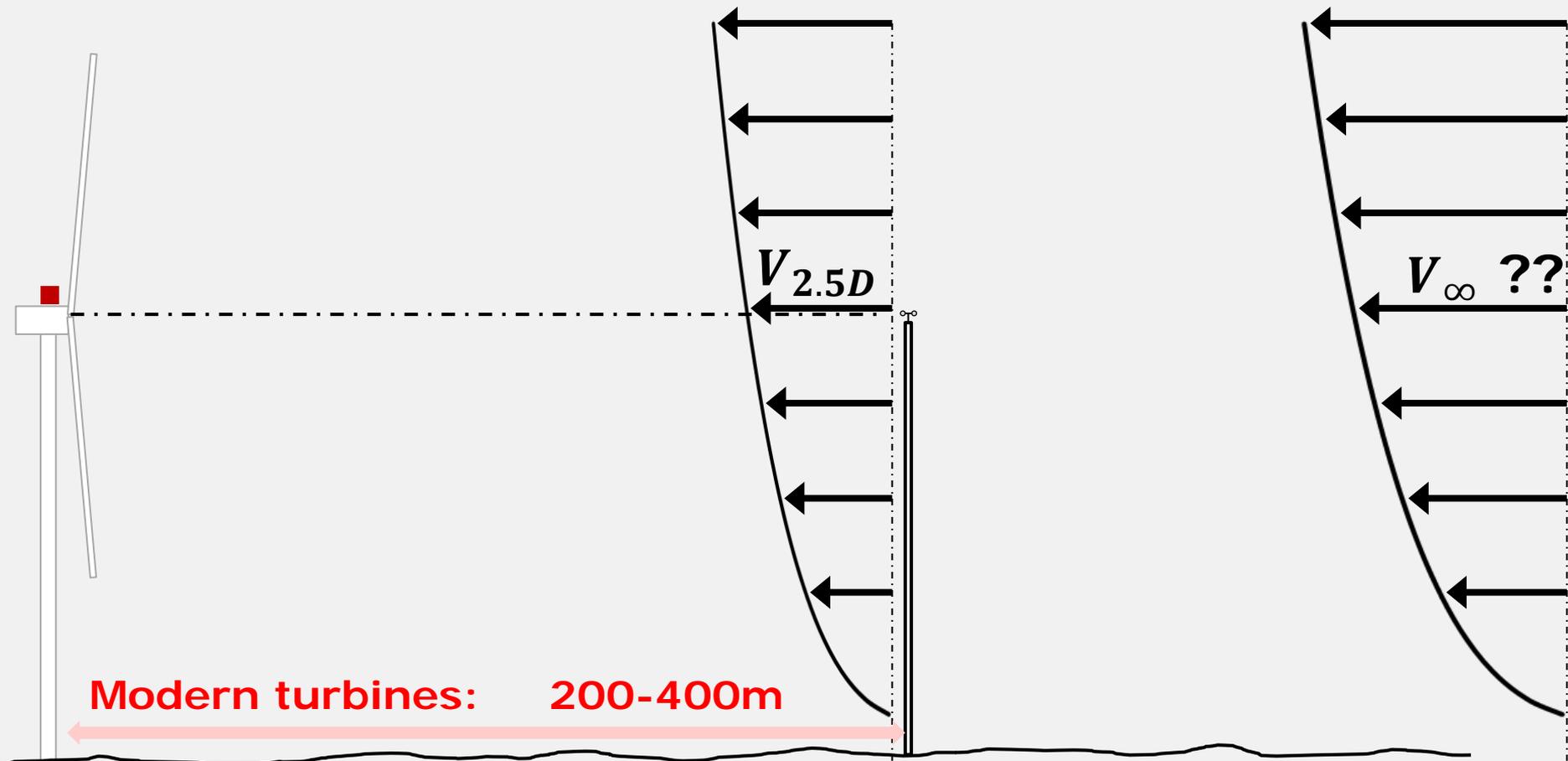
# Model-based wind field reconstruction

## • Wind models

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Inhomogeneous 2D + linear V shear	$U_w = v_0 + \delta_V \cdot (z_w - z_{hub})$ $\leftrightarrow U_I = f(z)$	$V_w = 0 \leftrightarrow V_I = V$	$W_w = 0 \leftrightarrow W_I = 0$	Yaw misalignment $\alpha_H = cst$
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<b>Inhomogeneous 2D</b> + power law shear + induction model	$U_w = f(x, z)$ $\leftrightarrow U_I = f(x, z)$	$V_w = 0$ $\leftrightarrow V_I = f(x, z)$	$W_w = 0 \leftrightarrow W_I = 0$	<b>1D Biot- Savard for induction fct</b>


 fitted wind characteristics are: free stream HWS  $U_\infty$ , yaw misalignment  $\alpha_H$ , shear exponent  $\alpha_{exp}$ , induction factor  $a$ .

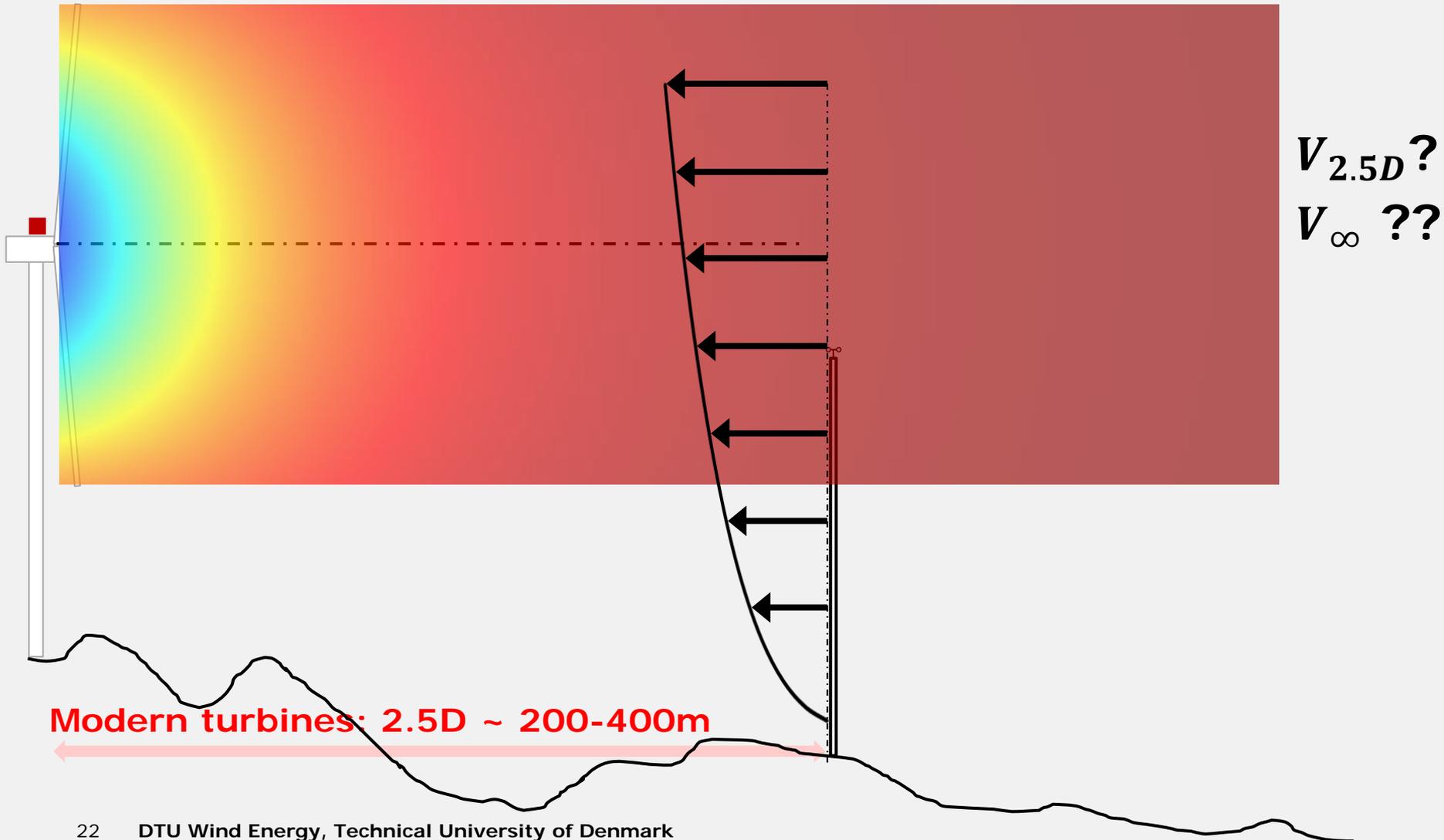
# Power performance verification: “standard” procedure, what’s the problem?



**Modern turbines: 200-400m**

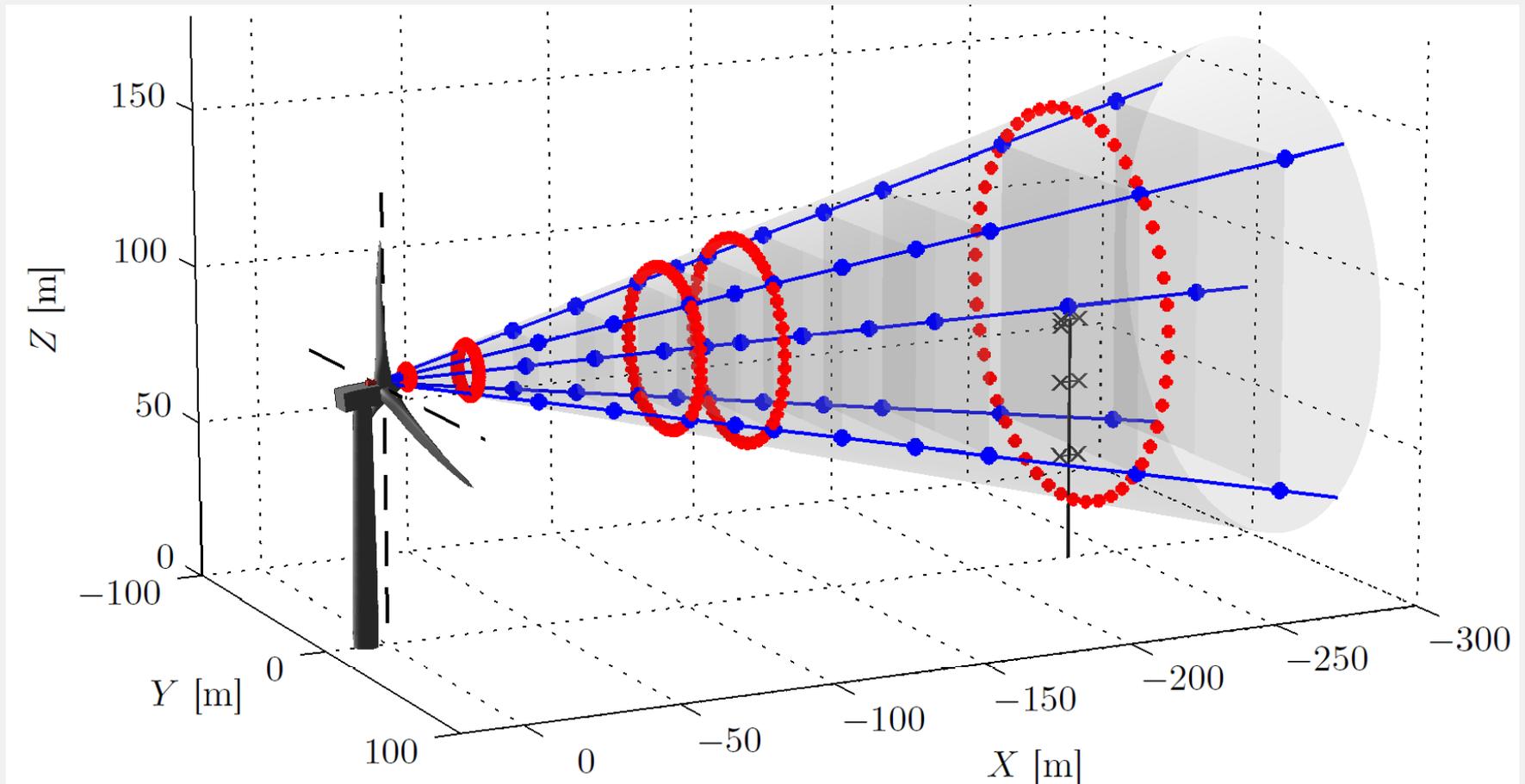
- Decorrelation WSpeed / power
- $H_{hub}$  speed insufficient?
- 2.5D not really free wind ...
- Too expensive: e.g. offshore

# Power performance verification: “standard” procedure, what’s the problem?



# Nørrekær Enge campaign (NKE), 7 months

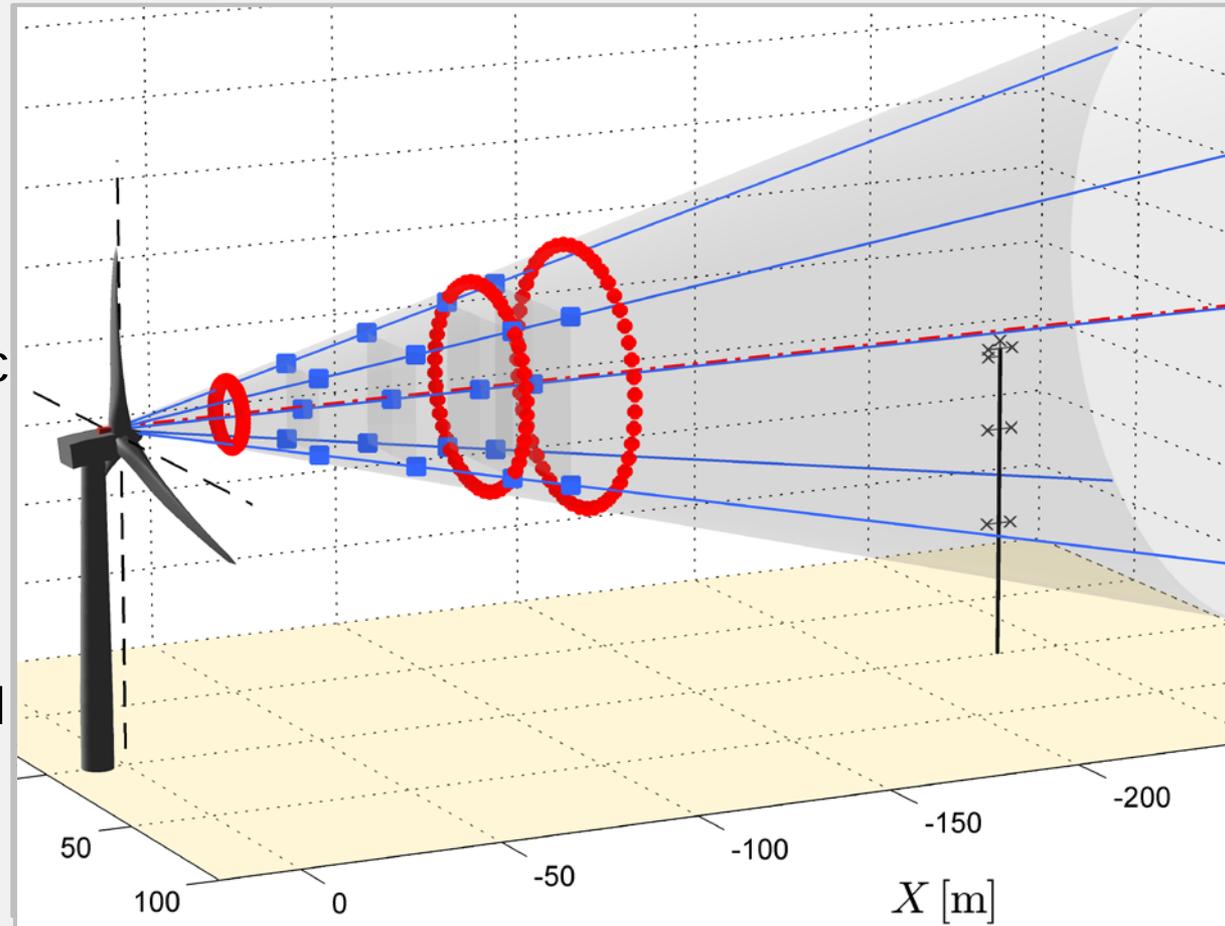
- Two nacelle lidars:  
Avent 5-beam (**5B**) **in blue**, ZephIR Dual Mode (**ZDM**) **in red**
- IEC compliant mast + SCADA + full loads



# Power performance verification: nacelle-mounted lidars, the future?

- Several possibilities for lidar measurements:

- 1) 2.5D distance  
incl. shear
- 2) 1D distance (only)  
+ correct with induc  
transfer function
- 3) Multiple distances  
from 0.5 to 1.5D  
induction integrated  
in wind field  
reconstruction



# A simple induction model

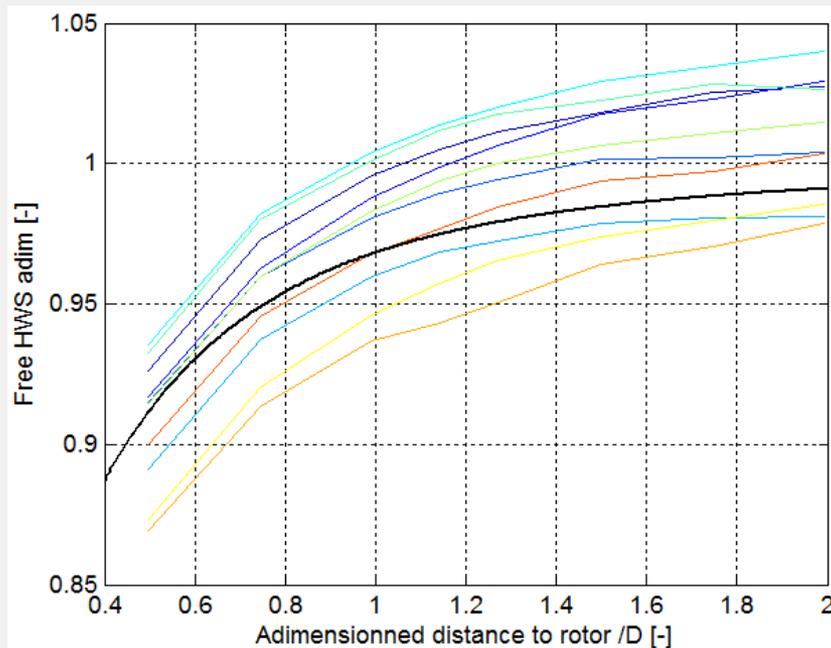
- **Derived from the Biot-Savart law**

- see [The upstream flow of a wind turbine: blockage effect](#)

- two parameters: induction factor  $a$ , free wind speed  $U_\infty$

$$\frac{U}{U_\infty} = 1 - a \left( 1 + \frac{\xi}{\sqrt{1+\xi^2}} \right), \text{ with } \xi = \frac{x_W}{R_{rot}}$$

- **What does the induction looks like in NKE?**



Black: theoretical,  $a = 0.3$

Colored lines: different 10min periods

→ Fitting  $a$  and  $U_\infty$  should be possible